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to event-based state estimation," conditionally accepted by IEEE Transactions on Automatic Control as a full paper, 2014. In all these papers, the ideas and technical results were developed by myself.

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(PDF) On Event Based State Estimation - ResearchGate

The goal of this paper is to develop a state estimation algorithm that can successfully cope with event based measurements. Firstly, we propose a general methodology for defining event based

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Event-based state estimation for a class of complex networks with time-varying delays: A comparison-principle approach. An event-triggered estimator is designed for complex networks with time-varying delays. A novel event generator function is proposed to reduce the communication burden. The comparison principle is

utilized to derive the sufficient conditions. The designed **Event-Triggered Least Squares Fault Estimation with**

...  
Proceedings of the 19th World Congress The International Federation of Automatic Control Cape Town, South Africa, August 24-29, 2014 **Event-Triggered Least Squares Fault Estimation with Stochastic Nonlinearities** LIU Yang , WANG Zidong , HE Xiao , ZHOU Dong-Hua , Department of Automation, Tsinghua University, Beijing, 100084, P. R. China.

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2. Problem Description. This paper deals with the localization and guidance of an autonomous vehicle using a state-space model and an external sensorial system based on cameras.

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