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The human hand and its dexterity in grasping and manipulating objects are some of the hallmarks of the human species. For years, anatomic and biomechanical studies have deepened the understanding

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A. Miller and P. Allen Department of Computer Science, Columbia University, New York, USA

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We study human grasping under a variety of conditions in order to identify and characterize different grasping strategies. Specially, we are interested in strategies that are robust to be performed under different kinds of impairment, e.g. visual. Our final goal, is to transfer those robust strategies to a robot.

A Taxonomy of Human Grasping Behavior for Transfer to ...

performance, it is only natural to replicate human grasping strategies on robots. A rst step towards this goal must be a characterization and analysis of human grasping behavior. This characterization should pay particular attention to the use of contact, i.e., the exploitation of contact constraints to compensate for uncertainty in perception or control. We derive a taxonomy of human grasping